

# Satellite Engineering

## Outlines

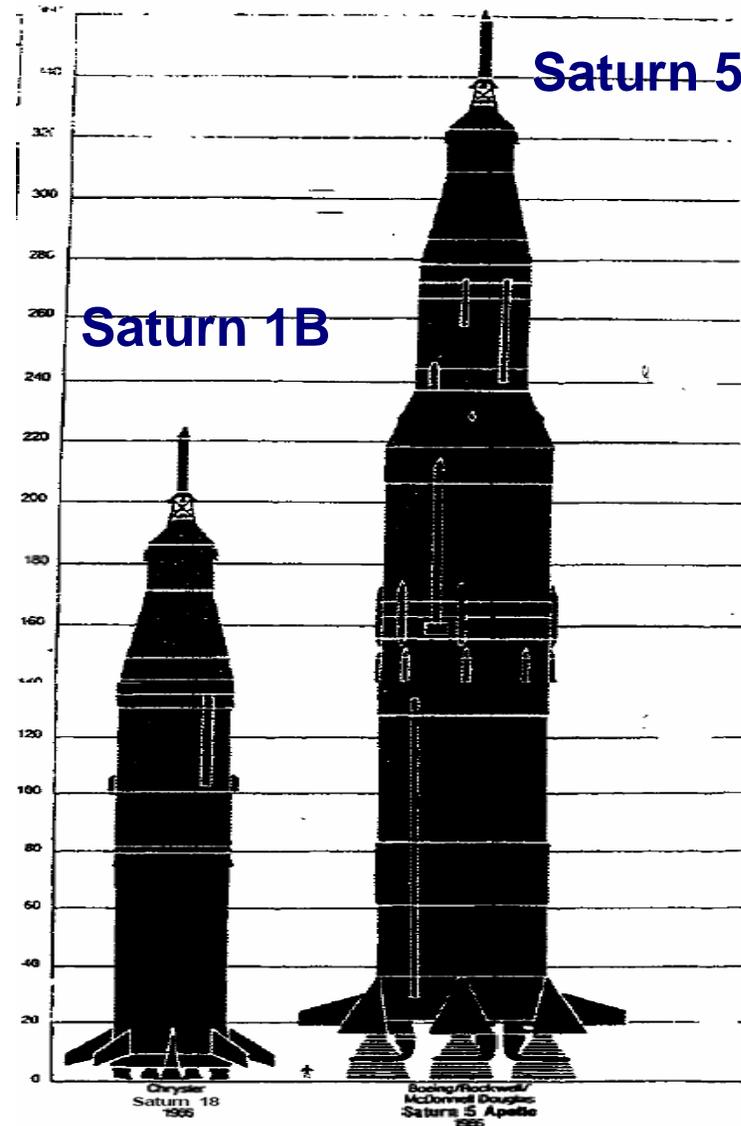
- Orbital Dynamics
- Launching
- Attitude Determination, control & Stabilization
- Thermal Design
- Spacecraft Power Subsystems
- Tracking Telemetry & Command
- Ground Support
- Spacecraft Structure

# Orbit Orientation

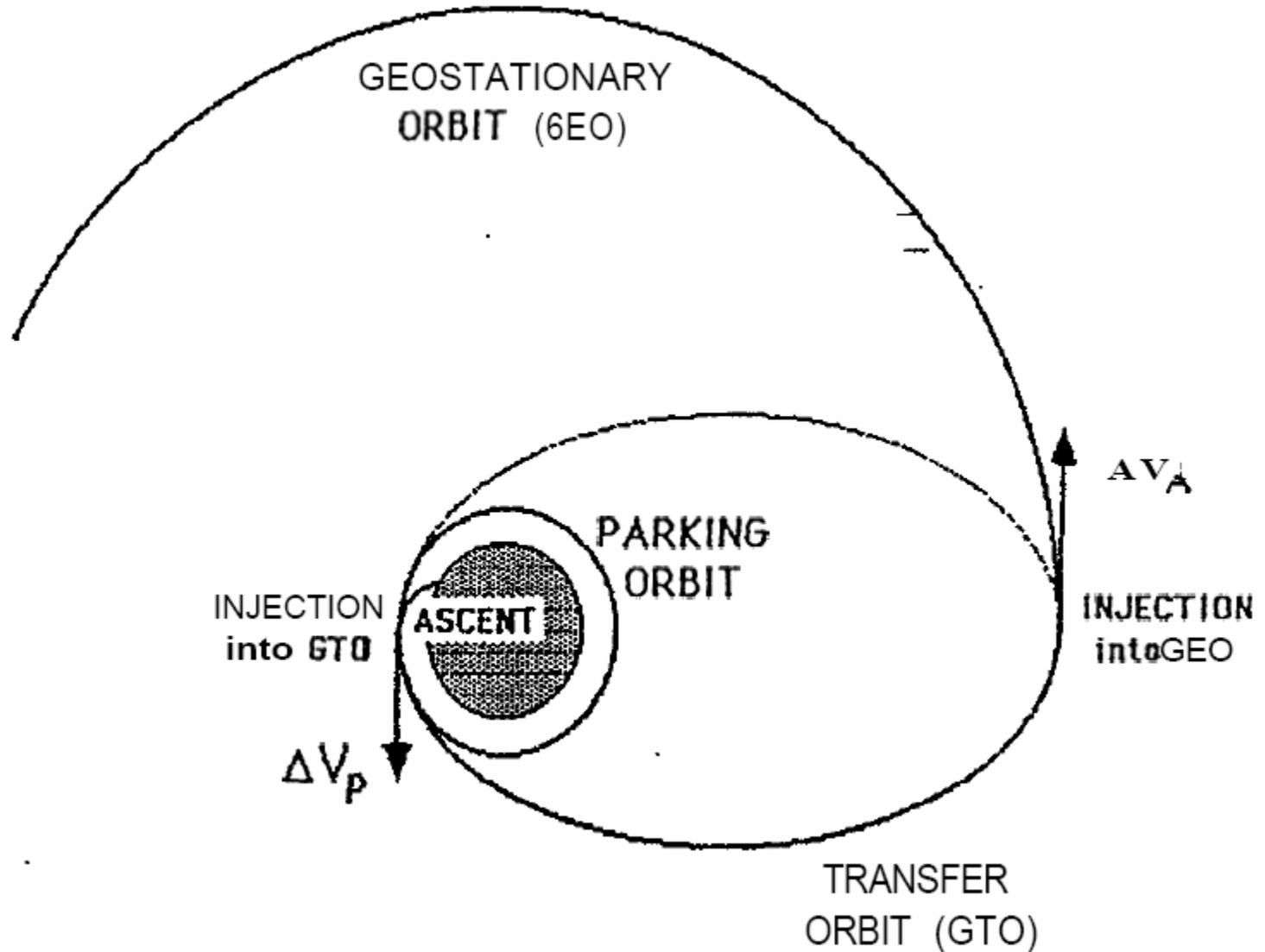
## Prograde & Retrograde Orbits

Inclination	Orbit Type	Diagram
$0^\circ$ or $180^\circ$	Equatorial	
$90^\circ$	Polar	
$0^\circ \leq i < 90^\circ$	Direct or Prograde (moves in direction of Earth's rotation)	 ascending node
$90^\circ < i \leq 180^\circ$	Indirect or Retrograde (moves against the direction of Earth's rotation)	 descending node

# Example of Launch Vehicles

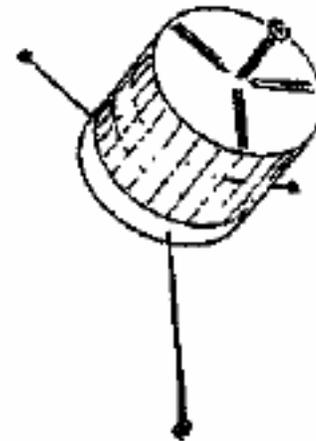
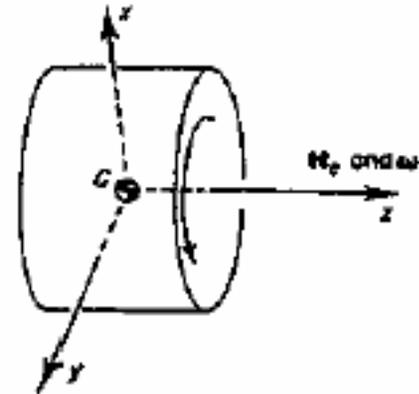


# LAUNCH PROCEDURE



# Spinning Spacecraft

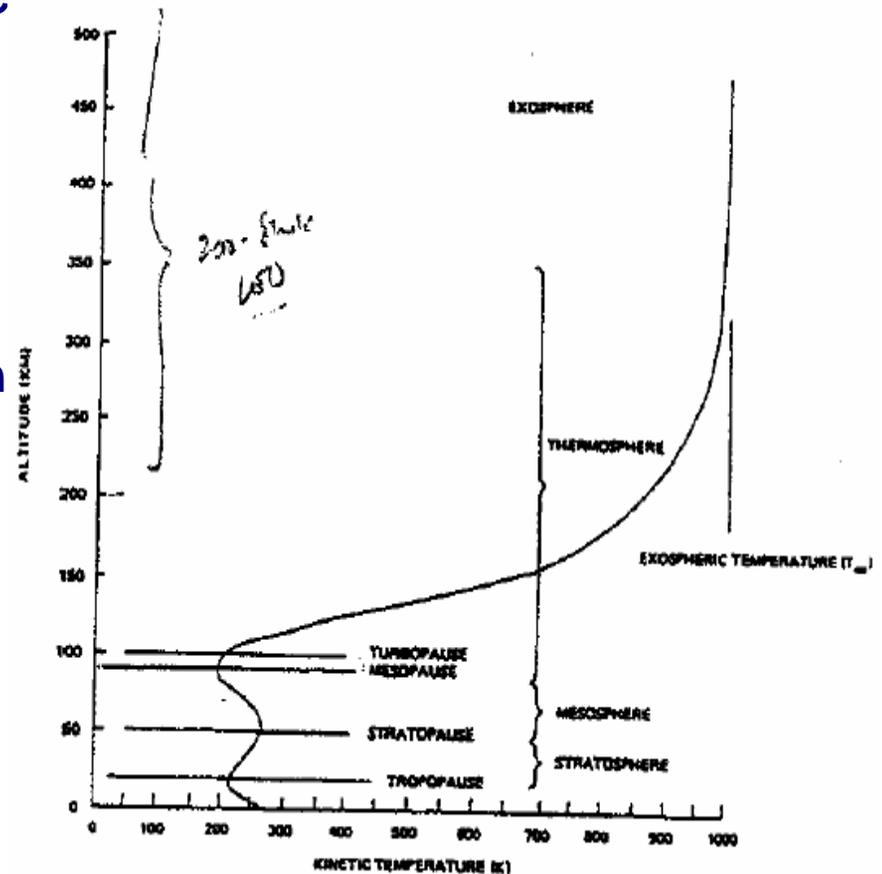
- The behavior of spinning (or part-spinning) satellites (i.e. those with a significant momentum bias) is complex, but is still described by the *Euler equations*.
- Typically, we want to achieve *gyroscopic rigidity*. However, in order to do this we must take care to choose the correct *spin axis*.
- the spin axis must be along an *eigenvector of the inertia matrix*, or put another way, angular rotation vector ( $\omega$ ) must be about a *principal axis*.



# Spacecraft Thermal Design

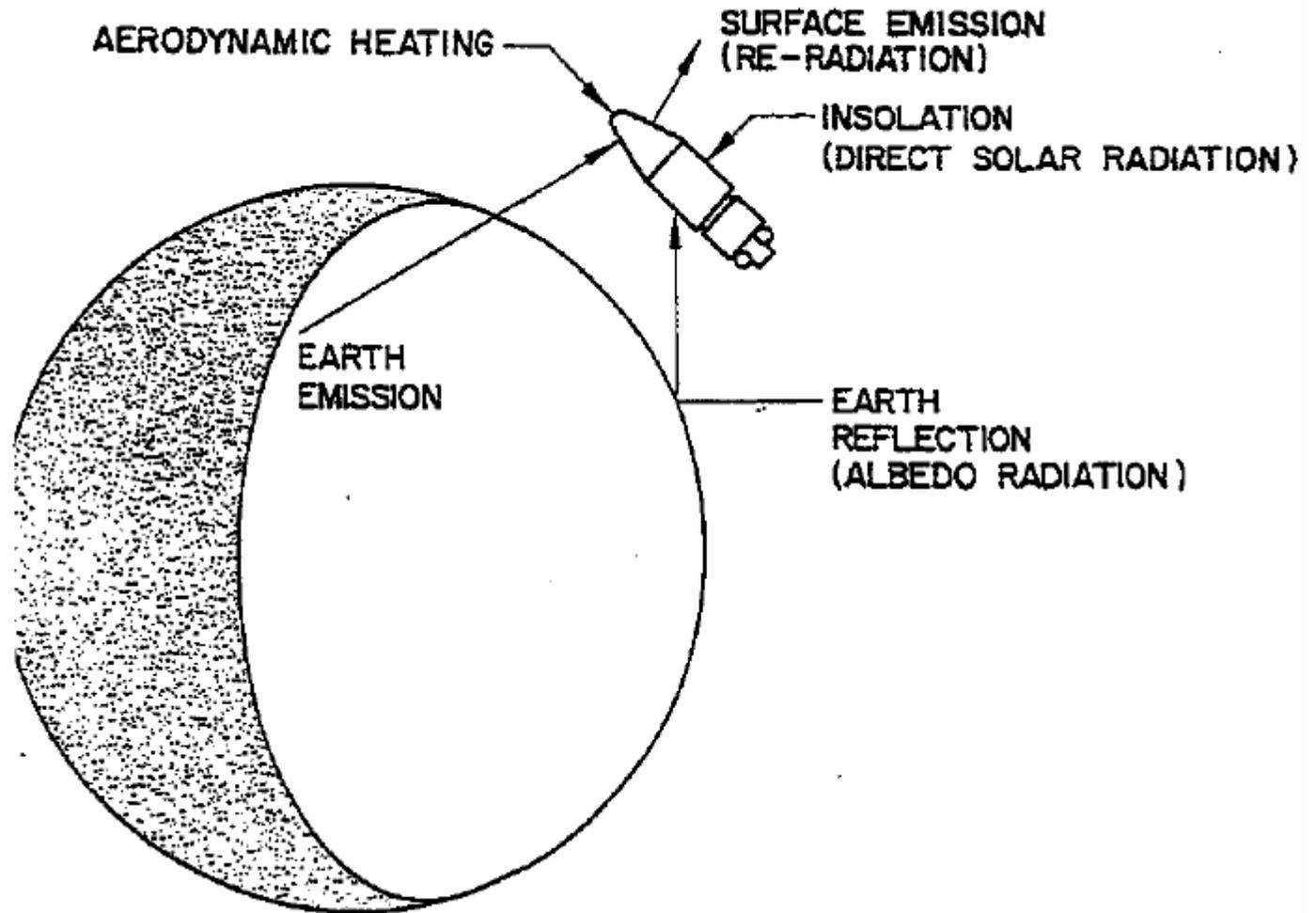
## Factors Controlling Temperature

- In near-Earth space, the temperature of the residual atmosphere (Exosphere) is  $\sim 1000\text{K}$  ( $1273^\circ\text{C}$ ).
- However, spacecraft will not attain thermal equilibrium with the atmosphere as the free-mean path of the atmosphere's particles is much larger than the spacecraft dimensions,
- Heat Transfer is by radiation.



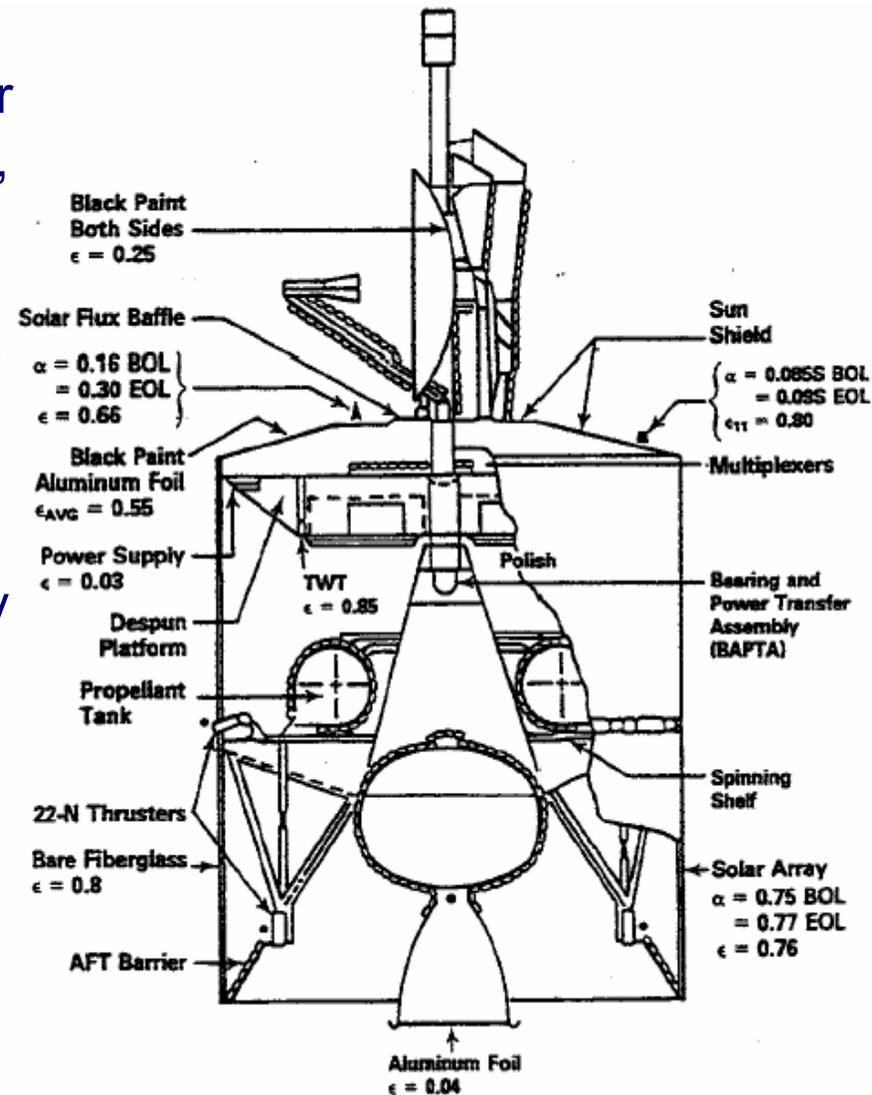
# Spacecraft Thermal Design

## Spacecraft Thermal Environment:

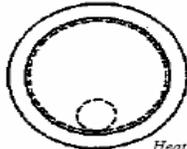
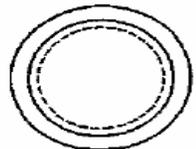
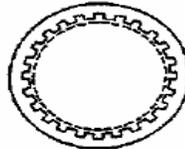
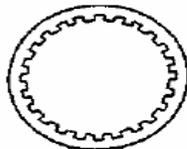
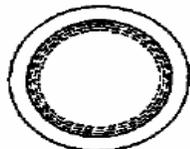
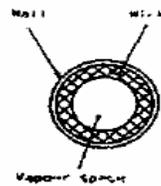
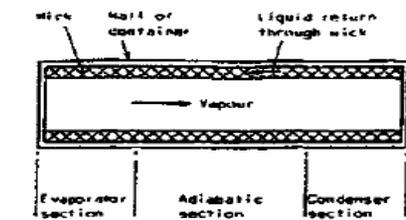


# Active Control using Louvers

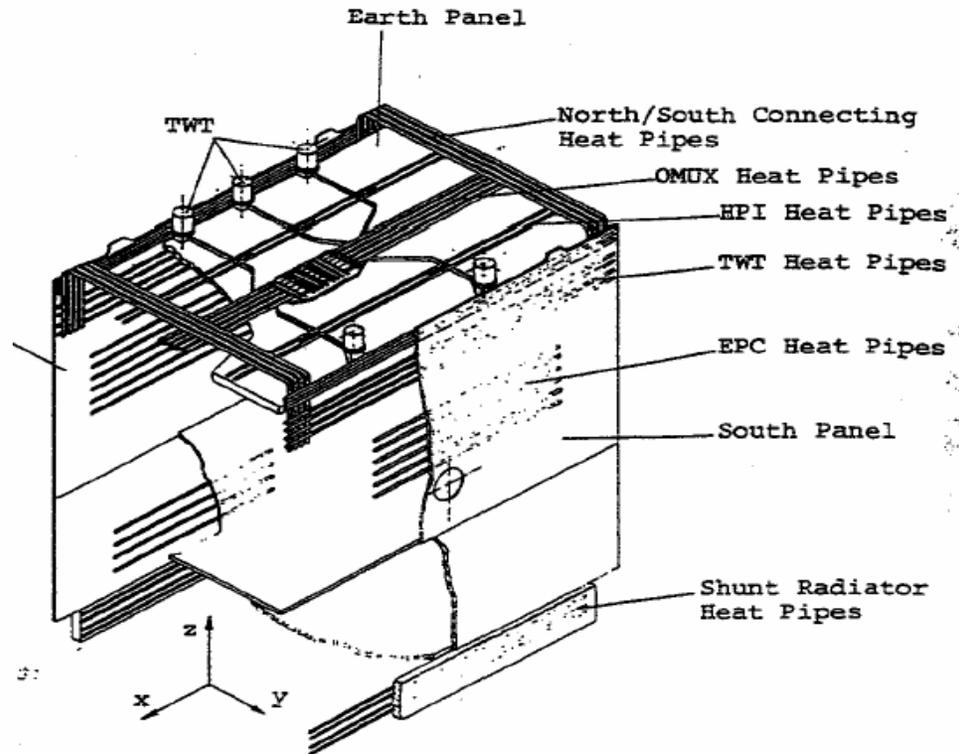
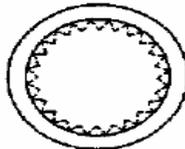
- Louvers consist of highly polished aluminum blades suspended on their ends along their length onto a frame, driven by bimetallic temperature sensors.
- The blades close at low temperatures to reduce heat lost to space.
- As the temperature increases, bimetallic temperature sensors apply torques that cause the blades to rotate to the open position increasing the heat rejected to space.
- Since the effective emittance to space changes with temperature, utilizing louvers greatly reduces any heater power requirements.



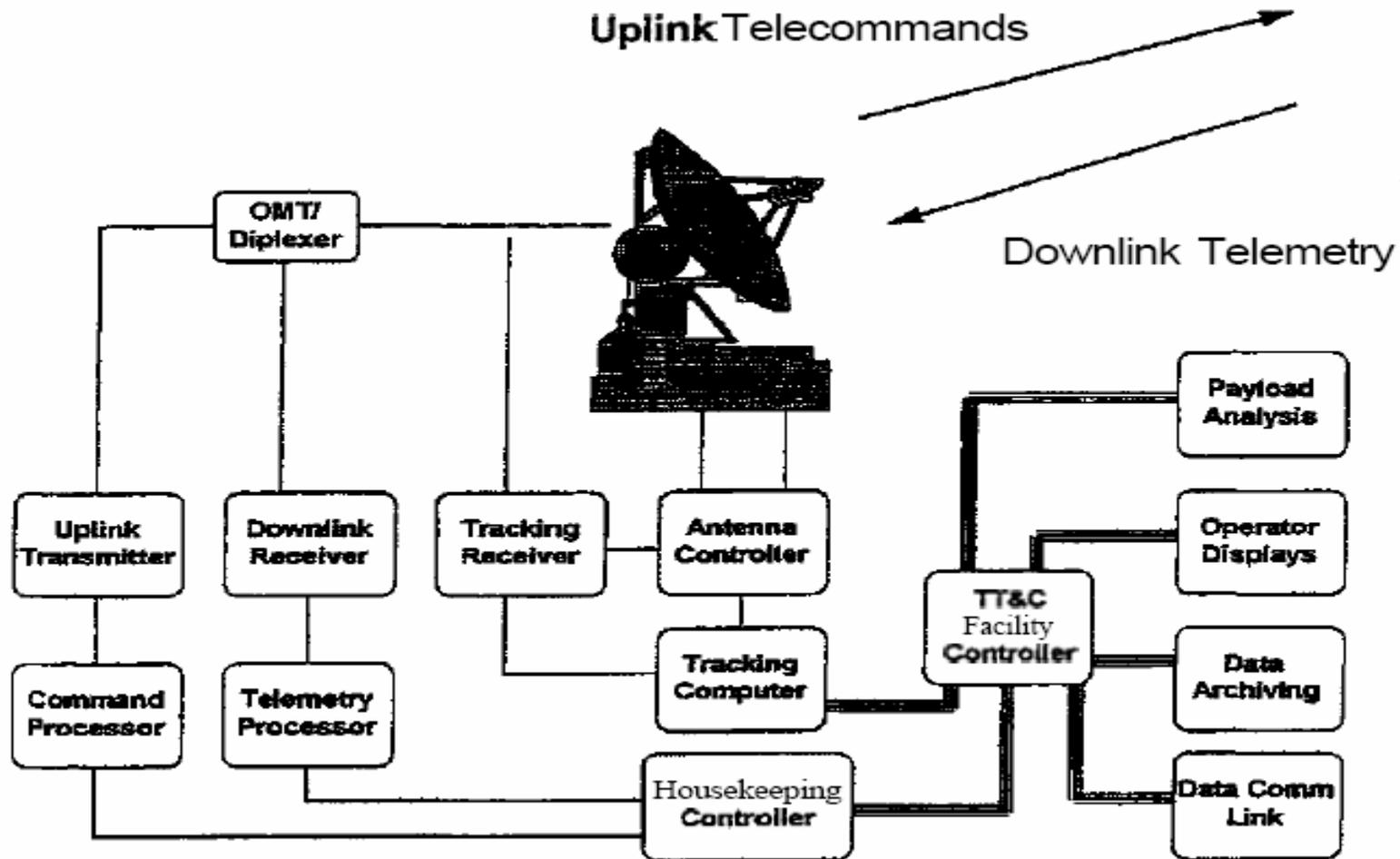
# Active Control using Heat Pipes



Heat pipe wall



# TT&C Facility



# Ground Support

- Design of the ground infrastructure depends upon
  - mission application
  - data distribution requirements
- Ground Support comprises a wide range of activities - before and after launch
  - Ground Test & launch campaign
  - In Orbit Test & commissioning
  - Earth Station Engineering

